

Multiphase Generators and Drives

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ENERPY 2019

- 1. Something about me ...
- 2. Multiphase machines
 - 1. Applications
 - 2. Control
- 3. Conclusions



PhD degree in Electrical and Electronic Engineering from the University of Seville, Spain, in 1998.

Full Professor at the University of Seville since Nov 2016.

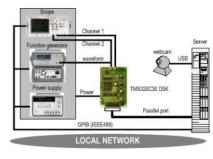
Interesting research fields: Control of electrical drives: multiphase ones in recent times Embedded systems in ITS

CV full details:

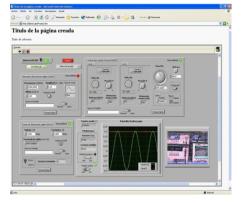
University of Seville:http://investigacion.us.es/sisius/sis_showpub.php?idpers=3201Researcher ID:A-9626-2013Google Scholar:http://scholar.google.com/citations?user=B4ouwAgAAAAJ&hl=esResearch Gate:https://www.researchgate.net/profile/Federico_Barrero

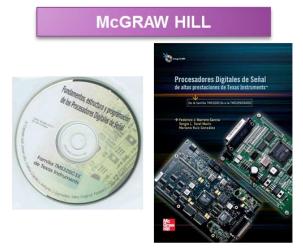
TEACHING EXPERIENCE

- 24 years of teaching experience to undergraduate students at an Engineering School (University of Seville)
- 17 years of teaching experience to graduate students at an Engineering School (University of Seville)
- Teaching in 17 different courses in 5 Engineering Degrees (Electronic Engineering field at the University of Seville). Principal lecturer in 6 of these courses
- Teaching in 4 different courses in MSc Engineering Degrees (Electronic Engineering field at the University of Seville). Principal lecturer in 2 of these courses
- Supervisor of 12 completed PhD students
- Supervisor of 12 MSc and 70 BSc final projects
- Principal lecturer in 9 innovative teaching projects. About 40 k EUR granted
- 5 edited books in the embedded systems' field:



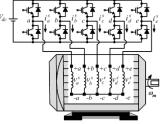
Remote labs for managing microprocessors (DSPs)

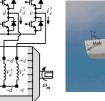




RESEARCH EXPERIENCE Research fields

Control of multiphase drives





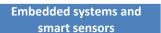






Research responsibilities

- More than 1.6 million EUR granted in total (public funds)
- More than 250000 EUR granted in total (private funds)
- Supervision of PhD Students: 12 completed students (2 in process)
- Researcher of ACETI research group









Embedded multimedia processors,

ITS Systems and Applications



RESEARCH EXPERIENCE

Research production

- ISI journals: more than 100
- About 180 conference papers

Awards and Recognitions

- Full Professor credentials from the Spanish Government since March, 2012
- Full Professor since 2016
- Senior member IEEE in 2005
- Best IEEE TIE paper award for the paper published in 2009
- Best IET EPA paper award for the paper published in 2010-2011
- Best conference paper award: 6



https://www.youtube.com/watch?v=LnV7lkZU-OY

Real Betis: https://www.youtube.com/watch?v=TFVfkZXQrEY

Multiphase Generators and Drives



http://www.us.es

| 1505 |
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| 85000 |
| 67 |
| 92 |
| 99 |
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http://www.esi.us.es



Campus de Excelencia Internacional with UMA

Alumni

6000

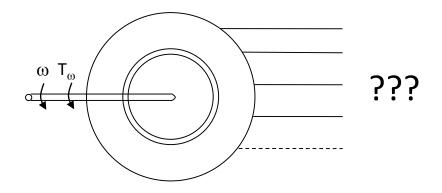
E. Levi, "Multiphase electric machines for variable-speed applications," *IEEE Trans. on Ind. Electron.*, vol. 55, no. 5, pp. 1893-1909, 2008.

E. Levi, "Advances in converter control and innovative exploitation of additional degrees of freedom for multiphase machines," *IEEE Trans. on Ind. Electron.*, vol. 63, 2016.

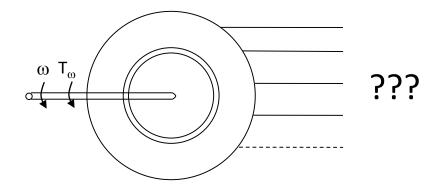
F. Barrero and M.J. Duran, "Recent advances in the design, modeling and control of multiphase machines – Part 1," *IEEE Trans. on Ind. Electron.*, vol. 63, 2016.

M.J. Duran and F. Barrero, "Recent advances in the design, modeling and control of multiphase machines – Part 2," *IEEE Trans. on Ind. Electron.*, vol. 63, 2016.

SS on "Multiphase Machines and Drives – Revisited" vol. 63 at TIE in 2016.



What does multiphase mean?



Why multiphase?

First of all ... Why not?
Machine supplied from converter ⇒ Any number of phases is feasible

Many advantages ...

- The power is splitted (lower stator losses)
- The fault-tolerant operation is allowed
- There is harmonic cancellation (ripple, vibration, noise)
- Torque enhancement is allowed (concentrated windings)
- More stability can be obtained
- Multi-motor drives can be used

Other considerations ...

The concept is not new, the origin of a six-phase generator can be traced back to 1929-1930: a machine with two in-phase three-phase winding was actually utilized in the States.

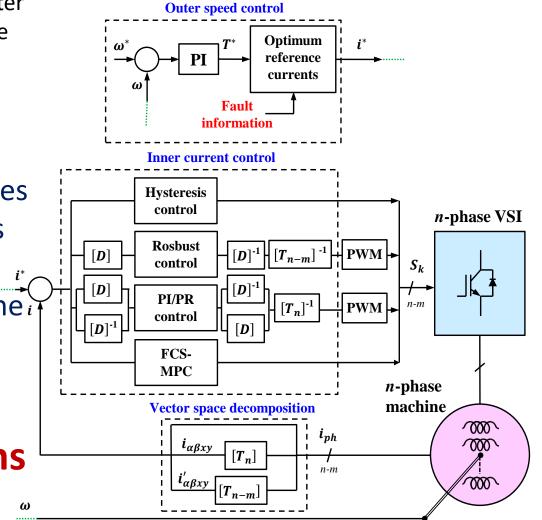
Now both signal processing and power electronics are adequate for its use and the topic has re-emerged.

Emerging applications are suitable for the use of multiphase drives.

Intrinsic features: power splitting, better fault tolerance or lower torque ripple than three-phase machines

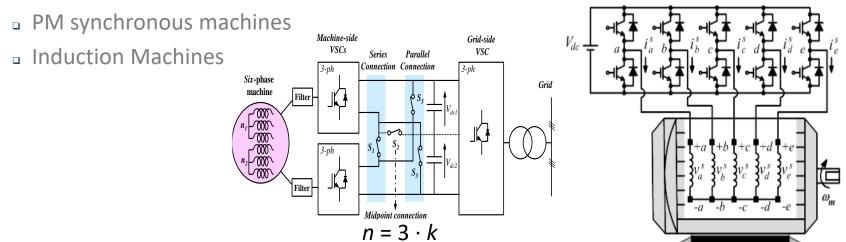
Attractive alternative to conventional three-phase ones in a number of applications where high overall system <u>r</u> reliability and reduction in the total power per phase are required

Many, many problems to solve ...



- The <u>model</u> differs according to the type of winding (concentrated or distributes), the number of phases (odd or even), isolated/non-isolated neutrals
 Main Problem
- The machine can be modeled in different ways
- Main Problem (Complexity)

- Phase-variable model
- Vector decomposition approach (VSD)
- Double-dq approach
- The model depends of course on the type of machines



Phase variable model for distributed-winding machines

$$\begin{split} \underline{v}^{s} &= \underline{R}_{s} \underline{i}^{s} + \frac{d\underline{\psi}^{s}}{dt} & \underline{\psi}^{s} = \underline{L}_{s} \underline{i}^{s} + \underline{L}_{sr} \underline{i}^{r} \\ \underline{v}^{r} &= \underline{R}_{r} \underline{i}^{r} + \frac{d\underline{\psi}^{r}}{dt} & \underline{\psi}^{r} = \underline{L}_{r} \underline{i}^{r} + \underline{L}_{rs} \end{split}$$

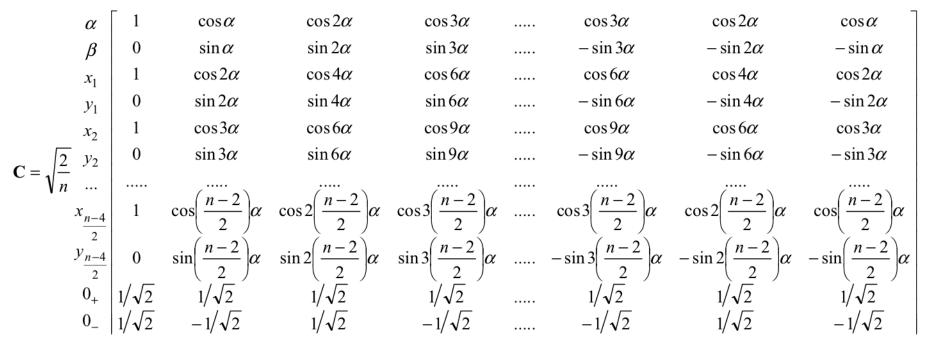
$$\begin{split} \underline{L}_{s} &= \begin{bmatrix} L_{11s} & L_{12s} & L_{13s} & \dots & L_{1ns} \\ L_{21s} & L_{22s} & L_{23s} & \dots & L_{2ns} \\ L_{31s} & L_{32s} & L_{33s} & \dots & L_{3ns} \\ \dots & \dots & \dots & \dots & \dots \\ L_{n1s} & L_{n2s} & L_{n3s} & \dots & L_{nns} \end{bmatrix} = \begin{bmatrix} L_{ls} + M & M \cos \alpha & M \cos 2\alpha & \dots & M \cos(n-1)\alpha \\ M \cos(n-1)\alpha & L_{ls} + M & M \cos \alpha & \dots & M \cos(n-2)\alpha \\ M \cos(n-2)\alpha & M \cos(n-1)\alpha & L_{ls} + M & \dots & M \cos(n-2)\alpha \\ M \cos\alpha & M \cos 2\alpha & M \cos 3\alpha & \dots & L_{ls} + M \end{bmatrix} \end{split}$$

$$\begin{split} \underline{L}_{r} &= \begin{bmatrix} L_{11r} & L_{12r} & L_{13r} & \dots & L_{1nr} \\ L_{21r} & L_{22r} & L_{23r} & \dots & L_{2nr} \\ L_{31r} & L_{32r} & L_{33r} & \dots & L_{3nr} \\ \dots & \dots & \dots & \dots & \dots & \dots \\ L_{n1s} & L_{n2r} & L_{n3r} & \dots & L_{nnr} \end{bmatrix} = \begin{bmatrix} L_{lr} + M & M \cos \alpha & M \cos 2\alpha & \dots & M \cos(n-1)\alpha \\ M \cos(n-1)\alpha & L_{lr} + M & M \cos \alpha & \dots & M \cos(n-1)\alpha \\ M \cos(n-2)\alpha & M \cos(n-1)\alpha & L_{lr} + M & \dots & M \cos(n-1)\alpha \\ M \cos(n-2)\alpha & M \cos(n-1)\alpha & L_{lr} + M & \dots & M \cos(n-2)\alpha \\ M \cos(n-2)\alpha & M \cos(n-1)\alpha & L_{lr} + M & \dots & M \cos(n-2)\alpha \\ M \cos(n-2)\alpha & M \cos(n-1)\alpha & L_{lr} + M & \dots & M \cos(n-3)\alpha \\ \dots & \dots & \dots & \dots & \dots \\ M \cos \alpha & M \cos 2\alpha & M \cos 3\alpha & \dots & L_{lr} + M \\ \end{split}$$

The model can be further simplified providing a better insight into the physical phenomena involved in the machine

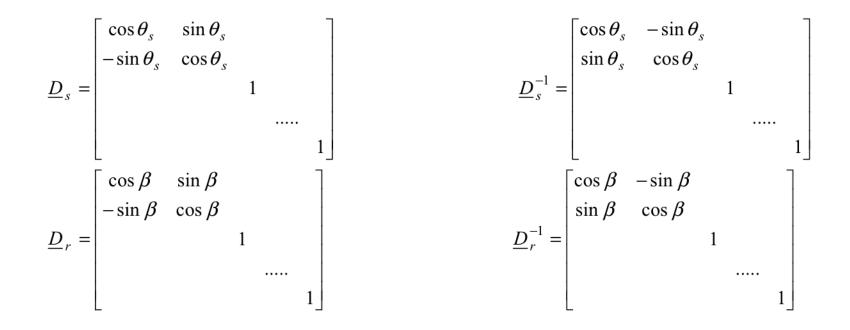
Vector decomposition approach (VSD)

It is a generalization of the Clarke/Park Transformation (power invariant) introduced by Zhao & Lipo to SIMPLIFY



The matrix is different if the number of phases is odd or even and if the neutrals are connected or isolated

The rotational transformation remains as in three-phase machines and just applies to α - β components, which are usually termed d-qwhen expressed in rotated frame.



Meaning of the components

- The first stator-rotor pair (α - β subspace) represents the fundamental supply component plus supply harmonic (of the order 12n±1 (n=1,2,3,...) in 6ph-machines).
- The other stator—rotor pairs (x—y subspace)represent supply harmonic (of the order 6n±1 with n=1,3,5,...).
- The rest of the components are the zero sequence harmonic components which disappear if isolated neutral points are assumed.
- NOTE: an important feature of the transformation is that all subspaces are orthogonal.

Differences in distributed and concentrated-winding machines

- In distributed-winding machines the x-y components are not involved in the electromechanical energy conversion process, the flux is mutually cancelled and the rotor is not linked. These components just generate stator Joule losses. NOT DESIRED.
- □ In concentrated-winding machines the x-y components (also termed d_3 - q_3 in five-phase machines) interact with the higher order spatial harmonics of the airgap and produce an additional torque. This leads to torque enhancement and higher power density. CAN DE OF INTEREST.

 $T_e = T_{e1} + T_{e3} = P(L_{m1} / L_{r1}) (\psi_{dr1} i_{qs1} - \psi_{qr1} i_{ds1}) + 3P(L_{m3} / L_{r3}) (\psi_{dr3} i_{qs3} - \psi_{qr3} i_{ds3})$

APPLICATIONS

PROPOSED APPLICATIONS TIED TO TYPE OF MULTIPHASE MACHINE

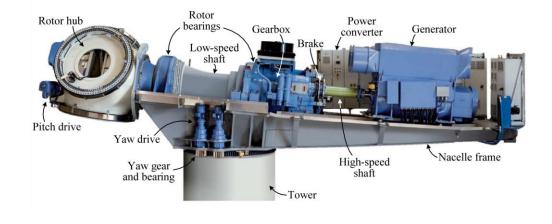
| Type of machine | Ref. | Application | | |
|--------------------------|----------------|--|--|--|
| Induction Machine | [8] | Submersible 5-phase pump motor | | |
| FSCW PM (SPM type) | [9,10] [17] | Fault-tolerant 6- and 5-phase in-wheel motor for electric vehicle 6-phase generator inside the aircraft main gas turbine engine | | |
| FSCW PM (IPM type) | [20] | 2.1 MW 5-phase marine propeller | | |
| BPM | [25] | 4- and 5-phase electromechanical flight control surface actuator | | |
| REL | [27] | 5-phase axial-flux configuration for electric vehicles | | |
| BLDC | [30] | 12 kW 5-phase electro hydrostatic actuator for aerospace application | | |
| Superconducting Machines | [34,35] | Design of 12 MW 9- and dual-3-phase synchronous generators | | |

MULTIPHASE GENERATION SYSTEMS (MACHINE AND POWER CONVERTER TYPE) IN PROPOSED APPLICATIONS

| Machine type | Converter type | Ref. | Applications |
|---------------------|--|--------------|--|
| PMSM (SPM type) | 3x BTB VSCs | [42] | 9-phase 1.1 MW generator in regenerative braking |
| PMSG | 4x BTB VSCs | [44] | 12-phase 5 MW WECS |
| Flux switching PMSG | 12x BTB VSCs | [45] | 36-phase 500 kW WECS |
| Axial flux PMSG | 9x series VSCs | [47] | 27-phase multi-MW WECS |
| PMSG (SPM type) | 4x series/parallel Vienna rectifier | [49] | 12-phase multi-MW WECS |
| SCIG | 2x DR + 1x VSC | [55] | 9-phase stand-alone WECS |
| WRSM/PMSM | 3x DR/DR+DC/DC | [61] [62] | 9-phase 2 MW shipboard DC generation system |

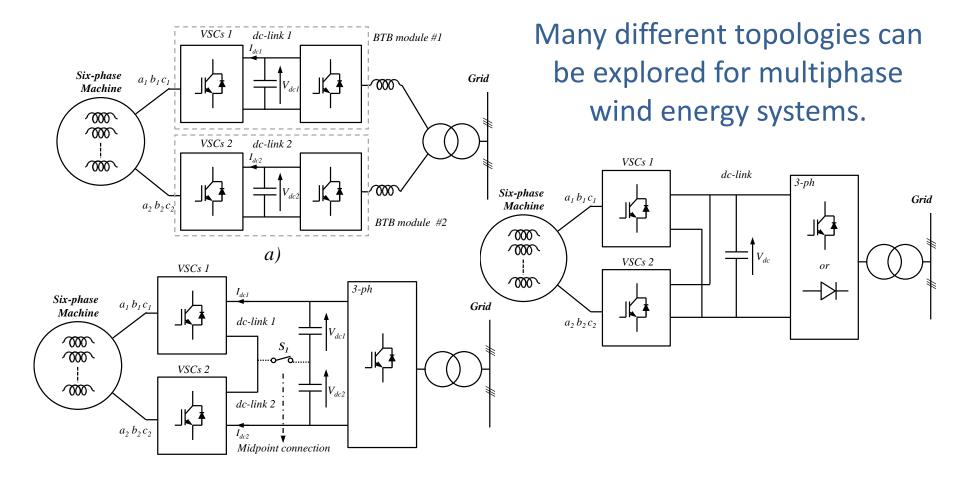
Electric generators in renewable energy



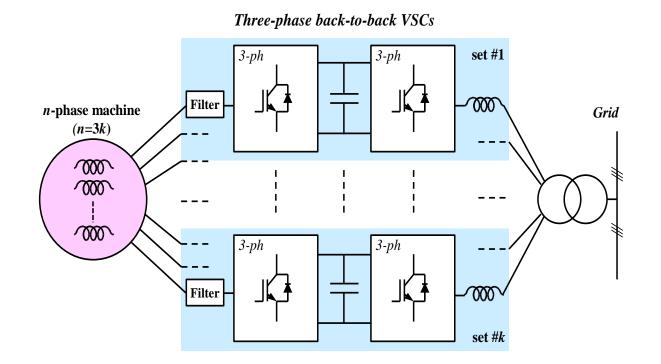


Most of these developments have been done using conventional threephase drives, but multiphase drives possess certain advantages that could make them a key player in the near future

Multiphase generating topologies

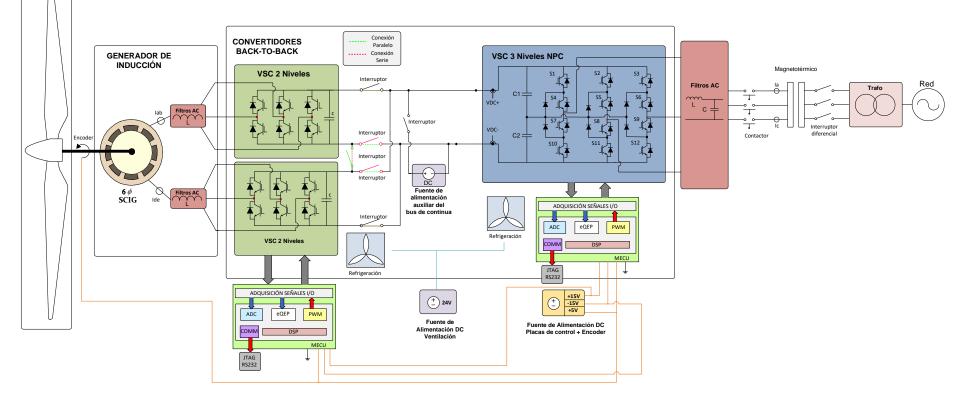


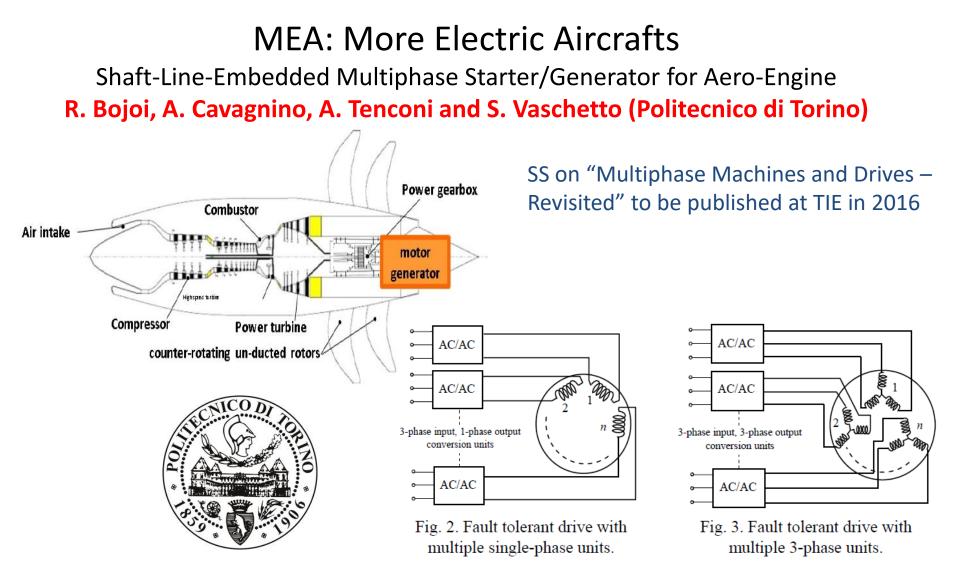
Examples of industry implementations are the multi-phase generators from GAMESA for 4.5 and 5 MW: 18-phase medium-speed PMSG drive using k=6 sets of three-phase windings and 750 kW IGBT-based BTB converters to reach 4.5 MW at 690 V.



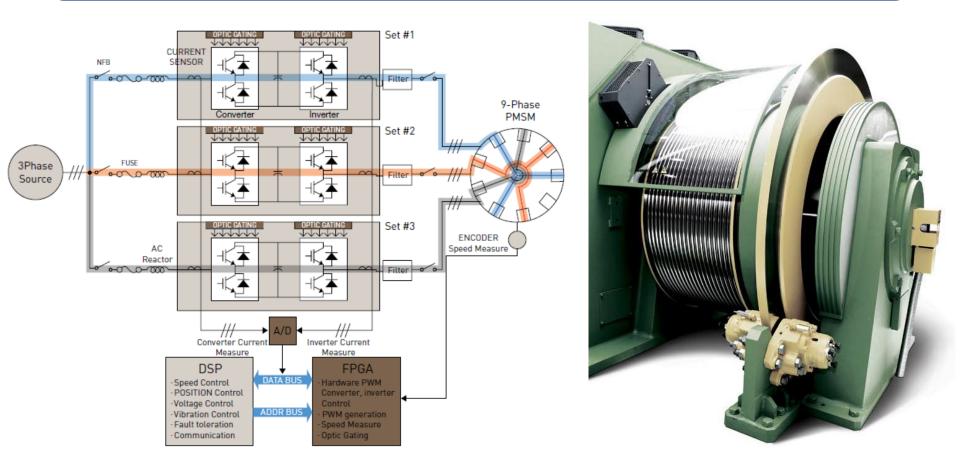








Hyundai High Speed Elevator 9-phase PMSM with three two level B2B converters



Submarines:

- 12-Phase PM (SIEMENS)
- 13-Phase PM







HMS Daring - March 2010

Electric propulsion in war ships: Type 45 destroyer

ALSTOM ('Advanced induction motor') 15-phase, 19 MW 3.7 kV, 0-15 Hz, 12-pole (150 rpm) 5 Isolated neutrals

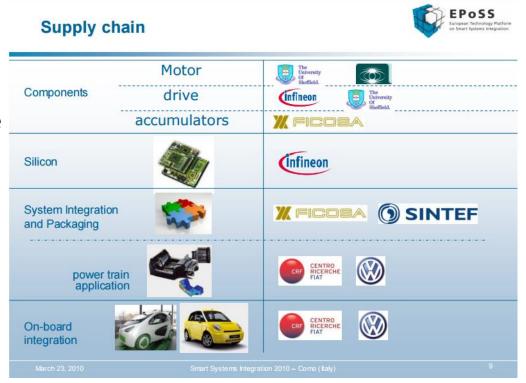




Integration of Multi propulsion power train European Green Vehicles Initiative (EGVI) through Grant No. 260176. Project acronym: CASTOR Project name: car multi propulsion integrated power train

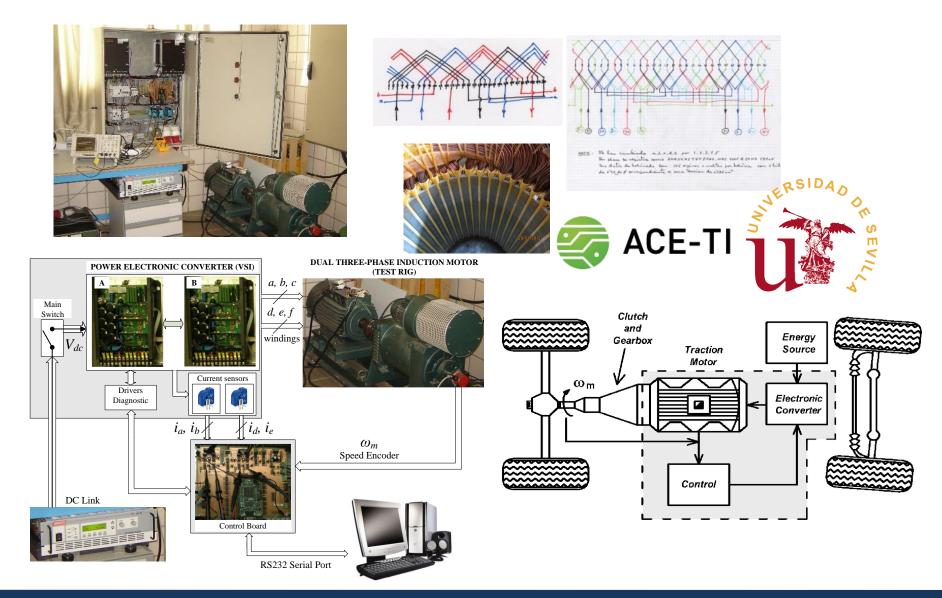
New winding configurations for 6-phase permanent magnet (18-slot, 8-pole, rated for 41kW peak power for electric vehicles) brushless machines that reduce undesirable space harmonics in the stator MMF are proposed.

A prototype machine drive (motor and inverter) is introduced and its architectural advantages are explored as a fully integrated powertrain for Electric Vehicle propulsion systems.



http://www.comarth.com/es/





V2G Applications



SS on "Multiphase Machines and Drives – Revisited" to be published at TIE in 2016

Reuse the existing inverter and propulsion multiphase machine in EVs during the battery charging process, achieving substantial savings on the space, weight and cost.

Symmetrical and asymmetrical six-phase machines are considered

Isolation is used off-board on the grid side.

The charging/V2G modes of operation are answered without torque production: rotor at standstill; mechanical lock avoided.

Fast charging due to less power limitation than in conventional single-phase chargers

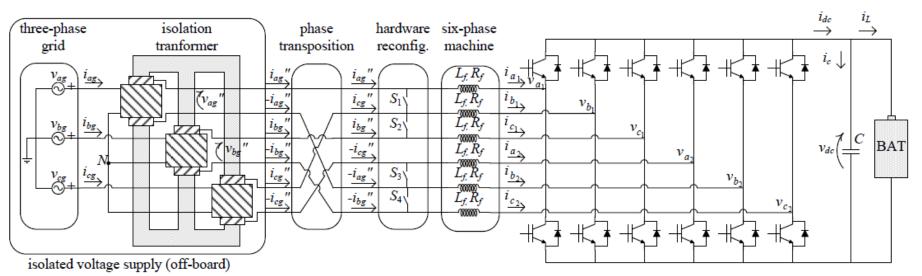


Fig. 1. Topology of the isolated charger incorporating a symmetrical six-phase machine. Grid connection system does not require a transformer with dual secondary (as in [15]) to create a symmetrical six-phase voltage supply for charging/V2G modes.

V2G Applications

Minor drawback

The proposal requires a hardware reconfiguration using four added switches for the charging/vehicle-to-grid modes of operation.

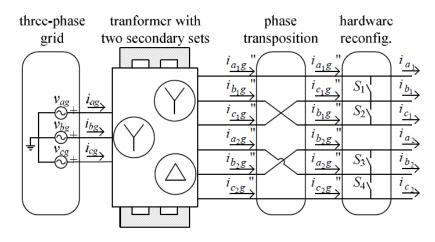
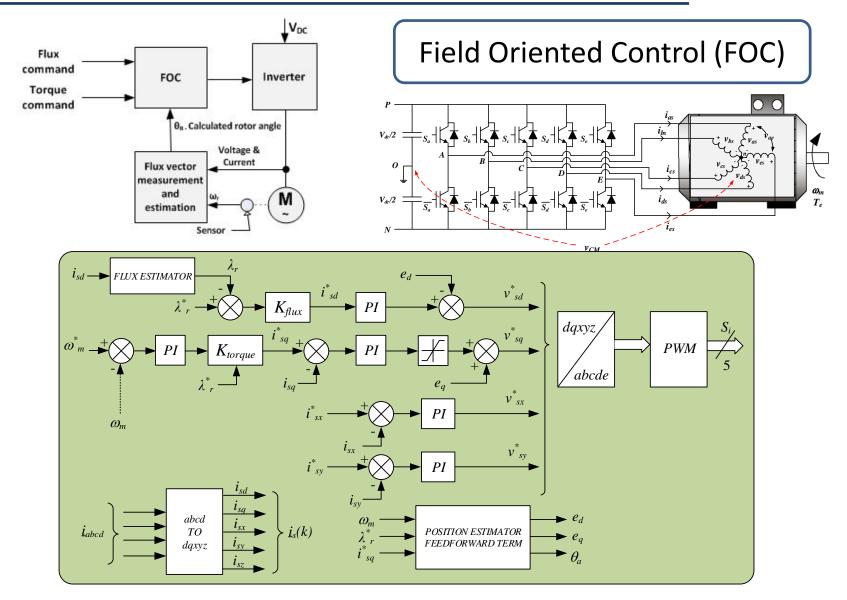
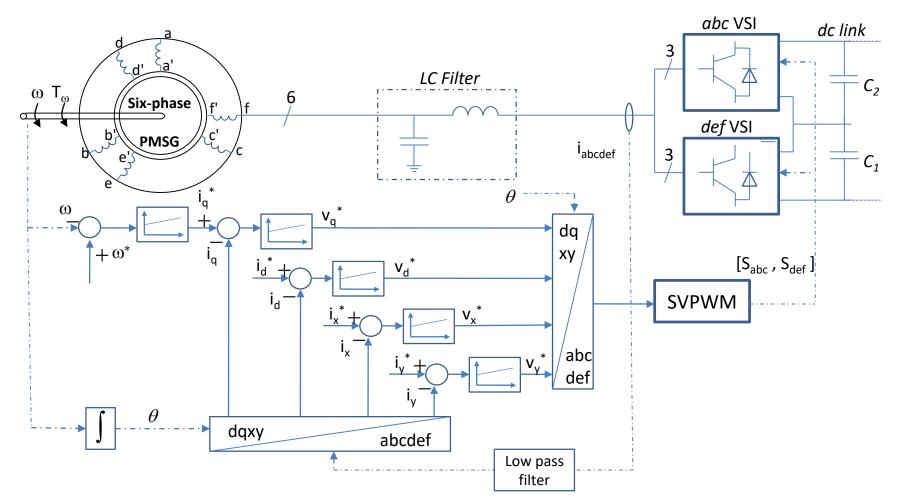


Fig. 2. Connections of isolated charger incorporating an asymmetrical sixphase machine (the right part is the same as in Fig. 1).

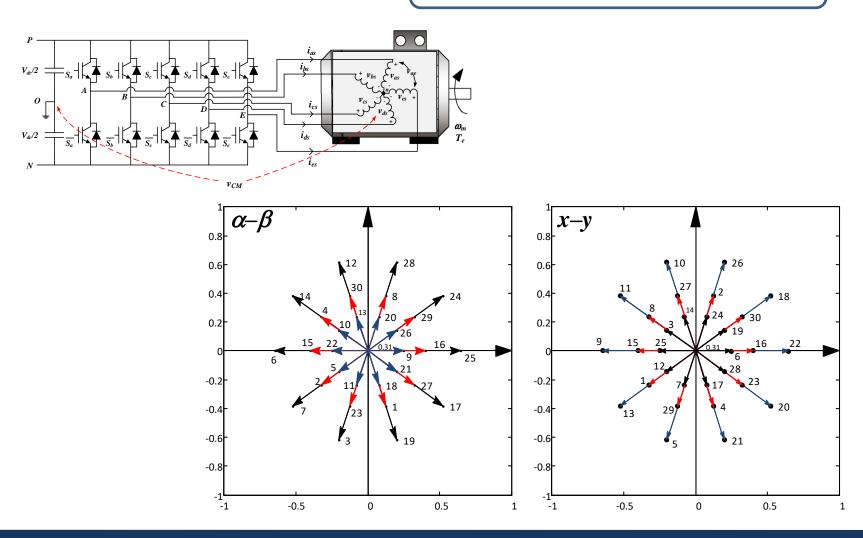




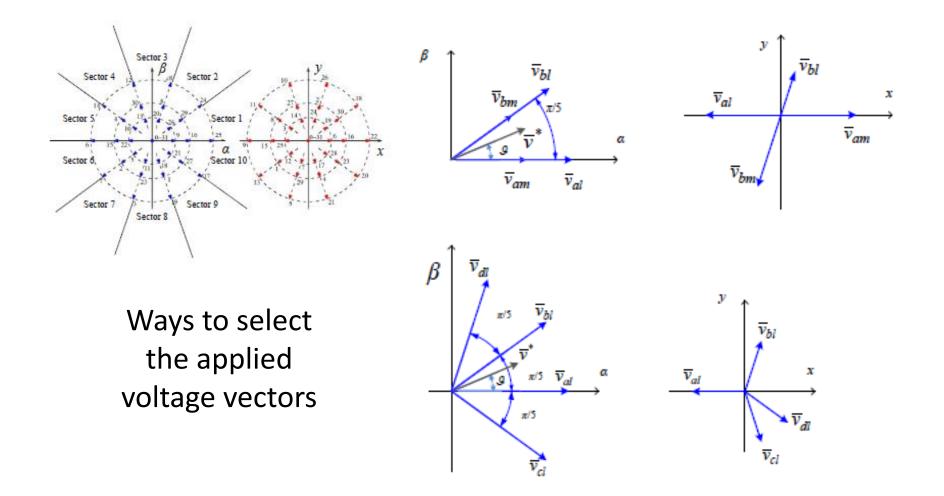
The classical control schemes remain basically the same but new controllers modified modulation techniques are necessary



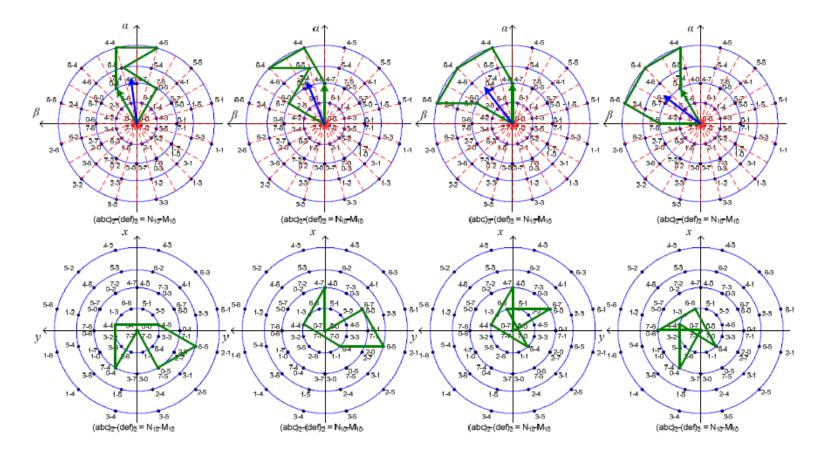
Field Oriented Control (FOC)



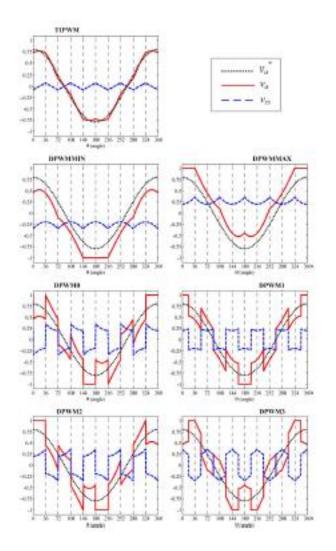
Multiphase Generators and Drives



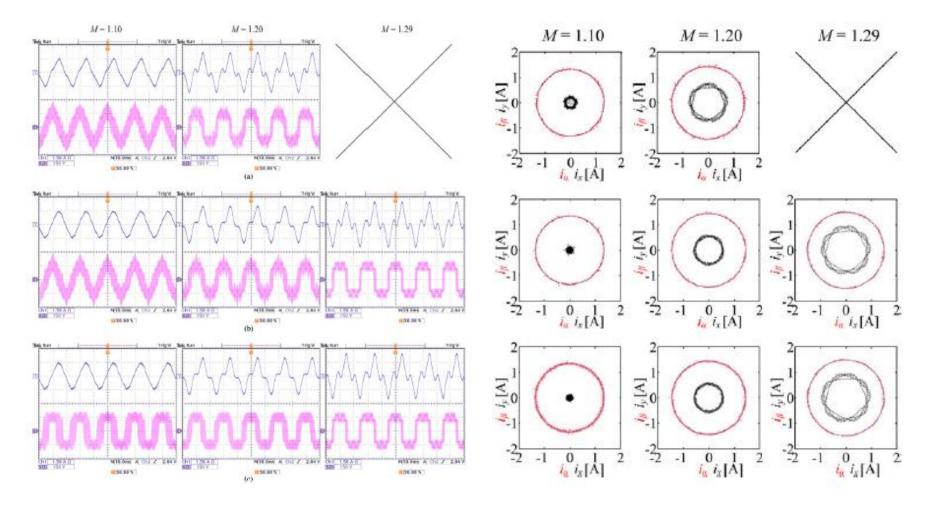
Ways to select the applied the sequence of voltage vectors and ZERO voltage vectors



Ways to find equivalencies between CPWM and SVPWM



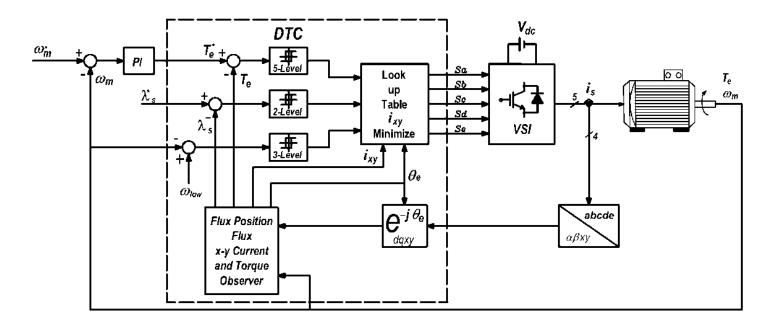
and ... What about overmodulation?



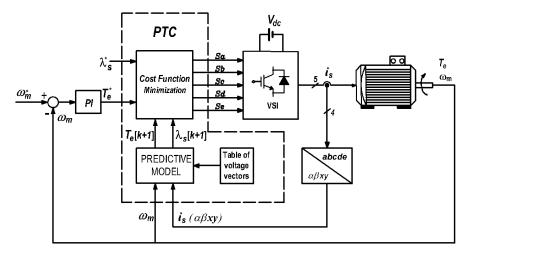
Other interesting control methods do not require any modulation technique:

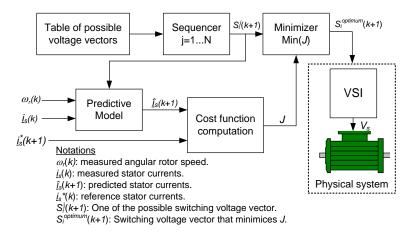
- DTC
- Predictive methods

DTC developed for three-phase machines has been extended to multiphase drives ...



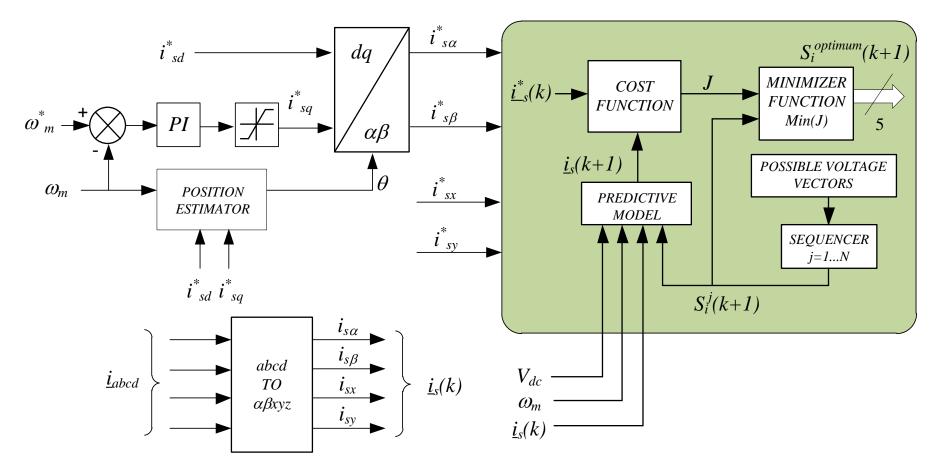
As well as Predictive torque and current control





$$J_{\alpha\beta xy} = \|\hat{e}_{\alpha\beta}\| + \|\hat{e}_{xy}\| = \left\|\hat{e}_{\alpha\beta} - \frac{\left[i_{\alpha}^{*}(k+1)-\hat{i}_{\alpha}(k+1|k)\right]^{2}}{R_{\alpha\beta}} + \frac{\left[i_{\beta}^{*}(k+1)-\hat{i}_{\beta}(k+1|k)\right]^{2}}{R_{\alpha\beta}} + \frac{\left[i_{\beta}^{*}(k+1|k)\right]^{2}}{R_{\alpha\beta}} + \frac{\left[i_{\beta}^{*}(k+1|k)$$

Example of a control scheme with an outer PI-based speed control and inner predictive-based current control.



After some hiccups, MMs have come back to stay

More technological developments are expected to improve their utility

New interesting applications based on them guarantee their final commercial use

i.e. fault tolerant or V2G technology



Multiphase Generators and Drives Federico Barrero

THANK YOU FOR YOUR ATTENTION